

Remote Control Operation Instructions



Remote Control Operation Instructions

STACKFORCE

栈擎

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Three-position lever:

Lowest position:
Uncontrollable servo
motors and wheel motors;

Middle position: Enables
servo motors;

Highest position: Enables
servo motors and wheel
motors.



Three-position lever:

Lowest position: Initial
calibration, leg height
control not available

Middle position: Enables
leg height control

Highest position: Enables
leg height and roll control

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- ① Press and hold to turn on the switch
- ② Move the upper left lever to the highest position
- ③ Move the upper right lever to the lowest position
- ④ Move the left joystick to the lowest position

② Move to the highest gear.

③ Move to the lowest setting

① On/off switch

④ Pull the joystick to its lowest position.



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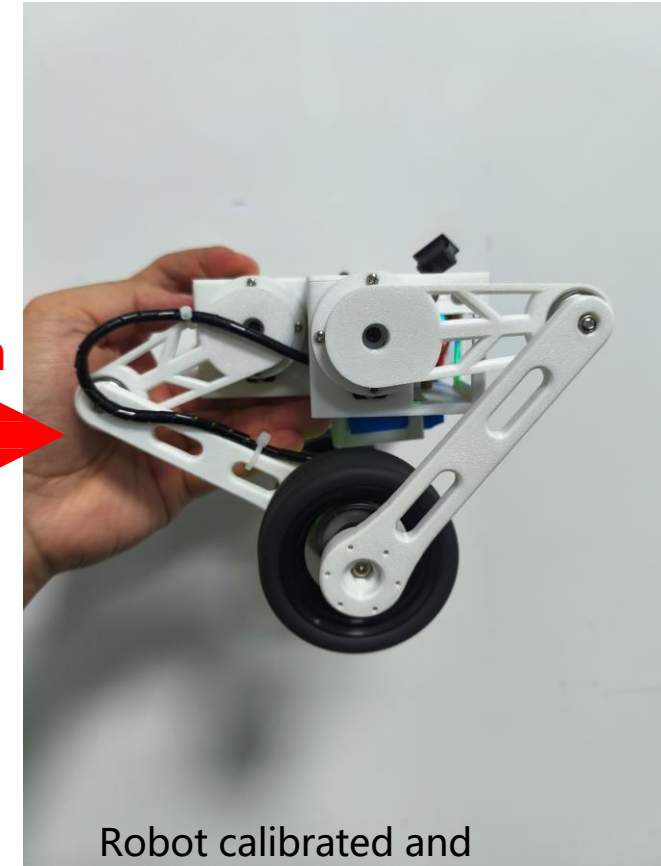
⑤ Turn on the robot switch, keep the robot suspended in the air and **parallel to the ground**, with its legs hanging down naturally, and **ensure that the wheels rotate smoothly** for calibration.

After calibration, the legs will return to their lowest height posture.



Handheld hovering robot
Keep the robot level with
the ground

After
calibration



Robot calibrated and
returned to its original
position

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⑥ After calibration, gently place the robot on the ground.

⑦ Move the right lever of the remote control to the highest position.

Now you can move the robot forward and backward, turn left and right, adjust its height, and adjust its roll!



Move to
the
lowest
setting.